# **20ES007 - Principles of Embedded Software**

# UNIT I:

Introduction: Compilers, Languages, and Object-Oriented Programming Embedded System Development – Debugging – More Challenges - Principles to Confront Those Challenges -Creating System Diagrams - The Block Diagram - Hierarchy of Control - Layered View - From Diagram to Architecture - Encapsulate Modules - Delegation of Tasks - Driver Interface: Open, Close, Read, Write, IOCTL - Adapter Pattern - Getting Started with Other Interfaces - Example: A Logging Interface.

# **UNIT II:**

**Hardware/SoftwareIntegration:** IdealProjectFlow - BoardBring-Up - ReadingaDatasheet. -Evaluating Components Using the Datasheet - Your Processor Is a Language - Reading a Schematic - Having a Debugging Toolbox (and a Fire Extinguisher) - Keep Your Board Safe -Keep Your Board Safe – Toolbox - Digital Multimeter - Oscilloscopes and Logic Analyzers -Testing the Hardware (and Software) -

Building Tests - Flash Test Example - Command and Response - Command Pattern - Dealing with Errors - Consistent Methodology - Error-Handling Library - Debugging Timing Errors.

### UNIT III: Outputs, Inputs, and Timers:

Toggling an Output - Starting with Registers - Set the Pin to Be an Output - Turn On the LED - Blinking the LED – Troubleshooting - Separating the Hardware from the Action - Board-Specific Header File - I/O-Handling Code - Main Loop - Facade Pattern - The Input in I/O - A Simple Interface to a Button - Momentary Button Press - Interrupt on a Button Press - Configuring the Interrupt - Debouncing Switches - Runtime Uncertainty - Dependency Injection - Using a Timer - Timer Pieces – Doing the Math.

### **UNIT IV: Managing the flow of Activity:**

Scheduling and Operating System Basics – Tasks - Communication Between Tasks -Avoiding Race Conditions - Priority Inversion - State Machines - State Machine Example: Stoplight Controller - State-Centric State Machine - State-Centric State Machine with Hidden Transitions - Event-Centric State Machine - State Pattern - Table-Driven State Machine -Choosing a State Machine Implementation.

### **UNIT V : Interrupts andCommunicatingwithPeripherals**

An IRQ Happens - Save the Context - Get the ISR from the Vector Table - Calling the ISR -Restore the Context - When to Use Interrupts - How Not to Use Interrupts – Polling - System Tick - Time-Based Events - A Very Small Scheduler - The Wide Reach of Peripherals - External Memory - Buttons and Key Matrices – Sensors – Actuators – Displays -PuttingPeripheralsandCommunicationTogether DataHandling -AddingRobustnesstotheCommunication ChangingData - Changing Algorithms. **TEXT BOOKS:** 

1. Making Embedded Systems (O'Reilly) - Elecia White, 2012, ISBN-13: 978-1-449-30214-6

 Embedded Systems Fundamentals with ARM Cortex-M based Microcontrollers: A Practical Approach (ARM Education Media UK) - Alexander G. Dean, 2017, ISBN-13: 978-1911531036

### Lab Experiments

To be able to learn about various C Programming tools To be able to learn about Arduino in detail.

- 1. Introduction to C Programming tools
- 2. Using Standard I/O
- 3. Using Conditionals
- 4. Using Loops
- 5. Intro to Addresses, Pointers and Handles
- 6. Interfacing with Arduino
- 7. Arduino Digital Output
- 8. Arduino Digital Input
- 9. Arduino Analog Input
- 10. Arduino Reaction Timer
- 11. Arduino Reaction Timer Redux
- 12. Arduino Analog Output via PWM
- 13. Arduino Event Counter
- 14. Arduino Arbitrary Waveform Generator